



Dermawan Pnup &lt;dermawan@poliupg.ac.id&gt;

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**[IIUMEJ] : "1254" Editor Decision - Accept**

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Dr. Ali Sophian &lt;iiumej@iium.edu.my&gt;

25 November 2019 06.40

Kepada: Dermawan Dermawan <dermawan@poliupg.ac.id>, Hammada Abbas <hammada.abbas@gmail.com>, Rafiuddin Syam <rafiuddinsyam@gmail.com>, Zulkifli Djafar <kifli\_djafar@yahoo.com>, Abdul Kadir Muhammad <kadir.muhammad@poliupg.ac.id>

Dear Dermawan Dermawan, Hammada Abbas, Rafiuddin Syam, Zulkifli Djafar, Abdul Kadir Muhammad:

Congratulation!!! According to our record, your manuscript ID #"1254", entitled "DYNAMIC MODELING OF A SINGLE-LINK FLEXIBLE MANIPULATOR ROBOT WITH TRANSLATIONAL AND ROTATIONAL MOTIONS" has been accepted for publication in the IIUM Engineering Journal (IIUMEJ).

We are requesting you to **upload** your camera ready manuscript based of the IIUM Engineering Journal by two weeks of this email in the discussion section by **Add discussion**. For details for preparation of manuscript, please visit journal website at <http://journals.iium.edu.my/ejournal/index.php/iiumej/about/submissions>

You can also find the Journal template and other related information in the **Submission Library** under **View Document Library** at the right top corner when click your paper title after login to the journal site.

You are also requested to update contributor author(s) if all authors name are not in the database by following the guidelines as mention in Update Author List in the Document Library.

You are also advised to pay publication processing fee of **RM 500.00 /USD 140** (*to coverup bank charge*)\_ (including GST) by two weeks of this email and send us the proof of payment by uploading in discussion section.

The payment can be made at following mode to bank account:

"By Cash Counter at BMMB, or Electronic Transfer or Telegraphic Transfer (TT) "

Name: UIAM Operating Account

Bank: **Bank Muamalat Malaysia Berhad**

Account No: **14070000004716**

Swift Code: BMMBMYKL

Branch: **International Islamic University Malaysia (IIUM)**, Gombak, Selangor

Country : Malaysia

Normally, the pre-publication process takes up to six months. During this period, galley proofs will be sent to you for checking and corrections purposes. The galley proofs must be returned to IIUMEJ within 7 calendar days. Furthermore, you are responsible for any error in the published paper due to your oversight.

Thank you for your contribution to IIUMEJ and we hope you will consider submitting an article to IIUMEJ again in the future.

Thanking you.

%

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IIUM Engineering Journal



Dermawan Pnup <dermawan@poliupg.ac.id>

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## [IIUMEJ] : "1254" Editor Decision - Revision Required

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Dr. Ali Sophian <iiumej@iium.edu.my>

23 November 2019 12.26

Kepada: Dermawan Dermawan <dermawan@poliupg.ac.id>, Hammada Abbas <hammada.abbas@gmail.com>, Rafiuddin Syam <rafiuddinsyam@gmail.com>, Zulkifli Djafar <kifli\_djafar@yahoo.com>, Abdul Kadir Muhammad <kadir.muhammad@poliupg.ac.id>

Dear Authors,

Thank you for the resubmission. There are still many English-related mistakes that need to be improved. We would like you to have another look. **I have attached a version with some proposed corrections**, which are not exhaustive, i.e. the authors still need to check other parts again as well. You may download the version and use it for the next resubmission.

Another note, in Section 5 Discussion, you have written "... motion in SLFM systems using MEH." Yet, no explanation I can find in the paper what MEH is. Please address this matter.

Please resubmit as soon as possible so we can include your paper in our next issue, inshaAllah.

Thank you.

Best regards,

Dr. Ali Sophian

[ali\\_sophian@iium.edu.my](mailto:ali_sophian@iium.edu.my)

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IIUM Engineering Journal



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**D-1254-Article Text-7217-1-15-20191108 as.docx**  
369K



Dermawan Pnup &lt;dermawan@poliupg.ac.id&gt;

**[IIUMEJ] : "1254" Editor Decision - Revision Required**

3 pesan

**Dr. Ali Sophian** <iiumej@iium.edu.my>

1 November 2019 08.41

Kepada: Dermawan Dermawan <dermawan@poliupg.ac.id>, Hammada Abbas <hammada.abbas@gmail.com>, Rafiuddin Syam <rafiuddinsyam@gmail.com>, Zulkifli Djafar <kifli\_djafar@yahoo.com>, Abdul Kadir Muhammad <kadir.muhammad@poliupg.ac.id>

Dear Authors,

Thank you again for your submission to IIUM Journal of Engineering.

With regard to your submission, titled "DYNAMIC MODELING OF A SINGLE-LINK FLEXIBLE MANIPULATOR ROBOT WITH TRANSLATIONAL AND ROTATIONAL MOTIONS", we would like you to make revisions based on the comments from the reviewers as attached below.

Thank you.

Best regards,  
Dr. Ali Sophian  
Section Editor

-----  
Reviewer A:  
Recommendation: Revisions Required

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Relevance of the title to the general content of the paper

Good

Relevance of the title to the domain of research addressed by author(s)

Good

Clear identification of the research problems

Fairly Good

Recomendation from the reviewer

Accepted with minor correction (The paper contains errors in grammar and presentation, minor improvements in the content of the research may also be required)

Comments and suggestions to authors

This paper presents the dynamic modeling of a single-link flexible manipulator robot with translational and rotational motion.

The English should be improved, too many grammatical errors such as "For the application of space robot, manipulator robot is designed to," should be "For the application of space robots, a manipulator robot is designed."

".. the SLFM system, which result in inaccurate positioning." should be "...the SLFM system, which results in inaccurate positioning."

These mistakes can be found for the rest of the manuscript.  
The word "namely" is overused; do try to find another more scientific word.

There is a font size difference in the Introduction, the beginning of the first paragraph is 11, and the rest is 12.

This dynamic modeling of a single-link flexible manipulator had been investigated by numerous studies. Therefore, the author should state the novelty and contribution clearly over other studies.

The author should write "comma" or "period" after all the equations to show the sentence is complete or not.

The author should check that all the symbols are explained, such as " $\varphi_{(i+1)}$ ", and what is the difference between "v" and "vp".

The author should include the result in the abstract and conclusion.

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Reviewer C:

Recommendation: Revisions Required

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Relevance of the title to the general content of the paper

Very Good

Relevance of the title to the domain of research addressed by author(s)

Excellent

Clear identification of the research problems

Very Good

Recommendation from the reviewer

Accepted with minor correction (The paper contains errors in grammar and presentation, minor improvements in the content of the research may also be required)


Comments and suggestions to authors

The author presents his research with good preparation. The problem stated that the model for a flexible manipulator robot is needed, both in translational and rotational movement. Accuracy improvement is also sought to be achieved in this study. Several things need to be considered to be revised. First, at the end of the discussion, the research results should be displayed quantitatively from the entire simulation data achieved. So that the comparison of the improvements achieved can be easily seen. Second, there should be a quantitative or qualitative comparison value for the results of simulations with similar models from one of the references. So, it can be concluded that this research has significant novelty. Finally, it would be better if the illustration of the whole robot is displayed.

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 **D-1254-Article Text-6852-3-2-20191004 no names.docx**  
373K


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**Dermawan Pnup** <dermawan@poliupg.ac.id>  
Kepada: Abdul Kadir Muhammad <kadir.muhammad@poliupg.ac.id>

1 November 2019 13.09

[Kutipan teks disembunyikan]

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 **D-1254-Article Text-6852-3-2-20191004 no names.docx**  
373K

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**Dermawan Pnup** <dermawan@poliupg.ac.id>  
Kepada: Rafiuddin Syam <rafiuddinsyam@gmail.com>

4 November 2019 09.33

Alhamdulillah, tabe pak, sudah ada balasan diterima dengan revisi minor. Insya Allah selesai dlm beberapa hari ini

----- Forwarded message -----

Dari: **Dr. Ali Sophian** <iiumej@iium.edu.my>


Date: Jum, 1 Nov 2019 08.42

Subject: [IIUMEJ] : "1254" Editor Decision - Revision Required

To: Dermawan Dermawan <dermawan@poliupg.ac.id>, Hammada Abbas <hammada.abbas@gmail.com>, Rafiuddin Syam <rafiuddinsyam@gmail.com>, Zulkifli Djafar <kifli\_djafar@yahoo.com>, Abdul Kadir Muhammad <kadir.muhammad@poliupg.ac.id>

[Kutipan teks disembunyikan]

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 **D-1254-Article Text-6852-3-2-20191004 no names.docx**  
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Dermawan Pnup <dermawan@poliupg.ac.id>

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## [IIUMEJ] : "1254" Editor Decision - Revision Required

2 pesan

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Dr. Ali Sophian <iiumej@iium.edu.my>

23 November 2019 12.26

Kepada: Dermawan Dermawan <dermawan@poliupg.ac.id>, Hammada Abbas <hammada.abbas@gmail.com>, Rafiuddin Syam <rafiuddinsyam@gmail.com>, Zulkifli Djafar <kifli\_djafar@yahoo.com>, Abdul Kadir Muhammad <kadir.muhammad@poliupg.ac.id>

Dear Authors,

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Please resubmit as soon as possible so we can include your paper in our next issue, inshaAllah.


Thank you.

Best regards,  
Dr. Ali Sophian  
[ali\\_sophian@iium.edu.my](mailto:ali_sophian@iium.edu.my)

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IIUM Engineering Journal

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Dermawan Pnup <dermawan@poliupg.ac.id>

23 November 2019 21.01

Kepada: "Dr. Ali Sophian" <iiumej@iium.edu.my>

Thank you, I will do that.

[Kutipan teks disembunyikan]



Dermawan Pnup <dermawan@poliupg.ac.id>

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## [IIUMEJ] : "1254" Editor Decision -Production

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Prof. Dr AHM Zahirul Alam <iiumej@iium.edu.my>

5 Januari 2020 09.13

Kepada: Dermawan Dermawan <dermawan@poliupg.ac.id>, Hammada Abbas <hammada.abbas@gmail.com>, Rafiuddin Syam <rafiuddinsyam@gmail.com>, Zulkifli Djafar <kifli\_djafar@yahoo.com>, Abdul Kadir Muhammad <kadir.muhammad@poliupg.ac.id>

Dermawan Dermawan, Hammada Abbas, Rafiuddin Syam, Zulkifli Djafar, Abdul Kadir Muhammad:

The editing of your submission, "DYNAMIC MODELING OF A SINGLE-LINK FLEXIBLE MANIPULATOR ROBOT WITH TRANSLATIONAL AND ROTATIONAL MOTIONS," is complete. We are now sending it to production.

Submission URL: <https://journals.iium.edu.my/ejournal/index.php/iiumej/authorDashboard/submission/1254>

Prof. Dr AHM Zahirul Alam  
International Islamic University Malaysia  
Phone +60361964529  
[zahirulalam@iium.edu.my](mailto:zahirulalam@iium.edu.my)

Dr AHM Zahirul Alam, CEng, FIEB, FBCS, SMIEEEE, MIET, MIEICE  
Professor & Editor,  
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Tel: + 6 03 6196 4529 Fax: + 6 03 6196 4488  
Web: <http://staff.iium.edu.my/zahirulalam>  
Email : [zahirulalam@iium.edu.my](mailto:zahirulalam@iium.edu.my)

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IIUM Engineering Journal



Dermawan Pnup &lt;dermawan@poliupg.ac.id&gt;

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**[IIUMEJ] : "1254" Proofreading Request (Author)**

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**Prof. Dr AHM Zahirul Alam** <iiumej@iium.edu.my>

5 Januari 2020 09.15

Balas Ke: "Prof. Dr AHM Zahirul Alam" &lt;zahirulalam@iium.edu.my&gt;

Kepada: Dermawan Dermawan &lt;dermawan@poliupg.ac.id&gt;

Dear Author

Your submission "DYNAMIC MODELING OF A SINGLE-LINK FLEXIBLE MANIPULATOR ROBOT WITH TRANSLATIONAL AND ROTATIONAL MOTIONS" to IIUM Engineering Journal now needs to be proofread by following these steps.

1. Log into the journal.
2. Click on the Submission title and go to **production** stage.
3. Download the **PDF** galley and proof the galley.
  4. If there is any correction then download copyedited **WORD** file from Copyediting stage and do necessary corrections (typographical and format) and upload **WORD** and **PDF** files at Production stage by clicking **Add galley** (Galley label as **WORD** and **PDF-C**) and reply us "Proof reading and correction done".
  5. If there is no correction, then reply to us "Proof reading done. No correction requires"
4. Send the reply in **Production Discussions** section within 3 days of this email.

Submission URL: <https://journals.iium.edu.my/ejournal/index.php/iiumej/authorDashboard/submission/1254>  
Username: {\$username}

Thanking you.

Dr AHM Zahirul Alam, CEng, FIEB, FBCS, SMIEEEE, MIET, MIEICE  
Professor & Editor,  
IIUM Engineering Journal  
Dept. of Electrical and Computer Engineering  
Faculty of Engineering  
International Islamic University Malaysia  
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Malaysia

Tel: + 6 03 6196 4529 Fax: + 6 03 6196 4488

Web: <http://staff.iium.edu.my/zahirulalam>Email : [zahirulalam@iium.edu.my](mailto:zahirulalam@iium.edu.my)

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IIUM Engineering Journal





Dermawan Pnup <dermawan@poliupg.ac.id>

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## [IIUMEJ] : "1254" Request for camera ready manuscript and publication fees

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**Prof. Dr AHM Zahirul Alam** <iiumej@iium.edu.my>  
Balas Ke: "Prof. Dr AHM Zahirul Alam" <zahirulalam@iium.edu.my>  
Kepada: Dermawan Dermawan <dermawan@poliupg.ac.id>

25 November 2019 07.31

Dear Author,

Please upload your final manuscript within **1 week of** this email based on Journal template and author guidelines mention in Journal website at <http://journals.iium.edu.my/ejournal> in order to consider your publication in **Jan 2020** issue (publication issue forwarded to Jan -July from June -Dec).

You can also find the Journal template in Submission Library under View Document Libray at right top corner when click your paper title.

You are also request to pay journal processing fee or **RM 500/ USD 140 (overseas transaction) within a week** for **January 2020** issue consideration. Payment details can be found at

<http://journals.iium.edu.my/ejournal/index.php/iiumej/Fee>

You can upload your final manuscript in this discussion .

Thanking you.

Executive Editor, IIUEJ

Dr AHM Zahirul Alam, CEng, FIEB, FBCS, SMIEEE, MIET, MIEICE  
Professor & Editor,  
IIUM Engineering Journal  
Dept. of Electrical and Computer Engineering  
Faculty of Engineering  
International Islamic University Malaysia  
Jalang Gombak, 53100 Kuala Lumpur  
Malaysia

Tel: + 6 03 6196 4529 Fax: + 6 03 6196 4488  
Web: <http://staff.iium.edu.my/zahirulalam>  
Email : [zahirulalam@iium.edu.my](mailto:zahirulalam@iium.edu.my)

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IIUM Engineering Journal



Dermawan Pnup &lt;dermawan@poliupg.ac.id&gt;

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**[IJUEJ] : "1254" Submission Acknowledgement : "DYNAMIC MODELING OF A SINGLE-LINK FLEXIBLE MANIPULATOR ROBOT WITH TRANSLATIONAL AND ROTATIONAL MOTIONS":**

3 pesan

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**Prof. Dr. AHM Zahirul Alam** <iijuej@iium.edu.my>  
Kepada: Dermawan Dermawan <dermawan@poliupg.ac.id>

4 Oktober 2019 15.55

Dear Author:

Thank you for submitting the manuscript, "DYNAMIC MODELING OF A SINGLE-LINK FLEXIBLE MANIPULATOR ROBOT WITH TRANSLATIONAL AND ROTATIONAL MOTIONS" of article ID# "1254" to IJUEJ Engineering Journal. With the online journal management system that we are using, you will be able to track its progress through the editorial process by logging in to the journal web site:

Manuscript URL: <https://journals.iium.edu.my/ejournal/index.php/iijuej/authorDashboard/submission/1254>  
Username: dhersud

If you forget to upload Ethical Agreement Form during submission then send Ethical Agreement Form to replying this email. Please download from IJUEJ Engineering Journal Dashboard - Right top corner -> Submission Library -> View Document Library -> Other -> You can find the form. The form can also be downloaded from the journal home page.

You are also requested to update contributor author(s) if all author names are not in the database by following the guidelines as mention in the Update Author List in the Document Library.

You are also advised to proposed three reviewers name.

If you have any questions, please contact me by citing article ID number. Thank you for considering this journal as a venue for your work.

Thanking you.

Prof. Dr. AHM Zahirul Alam

---

IJUEJ Engineering Journal

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**Dermawan Pnup** <dermawan@poliupg.ac.id>  
Kepada: "Prof. Dr. AHM Zahirul Alam" <iijuej@iium.edu.my>

4 Oktober 2019 16.44

Ethical Agreement Form

Sent from [Mail](#) for Windows 10

[Kutipan teks disembunyikan]

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 **ETHICAL PRINCIPLES AND STANDARDS AGREEMENT.pdf**  
1836K

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**Dermawan Pnup** <dermawan@poliupg.ac.id>

15 Oktober 2019 11.13

10/1/2020

Email Politeknik Negeri Ujung Pandang - [IIUMEJ] : "1254" Submission Acknowledgement : "DYNAMIC MODELING OF A SINGLE-LINK ...

Kepada: "Prof. Dr. AHM Zahirul Alam" <iiumej@iium.edu.my>

Good morning,

we want to ask, is the Turnitin checkup results with 17% of our writing not processed?

Thanks & Regards

[Kutipan teks disembunyikan]



Dermawan Pnup <dermawan@poliupg.ac.id>

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## [IIUMEJ] New notification from IIUM Engineering Journal

---

**Prof. Dr AHM Zahirul Alam** <iiumej@iium.edu.my>

6 Januari 2020 12.09

Balas Ke: "Prof. Dr. AHM Zahirul Alam" <zahirulalam@iium.edu.my>

Kepada: Dermawan Dermawan <dermawan@poliupg.ac.id>

You have a new notification from IIUM Engineering Journal:

There is new activity in the discussion titled "[IIUMEJ] : "1254" Proofreading Request (Author)" regarding the submission "DYNAMIC MODELING OF A SINGLE-LINK FLEXIBLE MANIPULATOR ROBOT WITH TRANSLATIONAL AND ROTATIONAL MOTIONS".

Link: <https://journals.iium.edu.my/ejournal/index.php/iiumej/authorDashboard/submission/1254>

Prof. Dr. AHM Zahirul Alam

---

IIUM Engineering Journal



Dermawan Pnup <dermawan@poliupg.ac.id>

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## [IIUMEJ] New notification from IIUM Engineering Journal

---

**Prof. Dr AHM Zahirul Alam** <iiumej@iium.edu.my>

3 Januari 2020 14.48

Balas Ke: "Prof. Dr. AHM Zahirul Alam" <zahirulalam@iium.edu.my>

Kepada: Dermawan Dermawan <dermawan@poliupg.ac.id>

You have a new notification from IIUM Engineering Journal:

There is new activity in the discussion titled "[IIUMEJ] : "1254" Request for camera ready manuscript and publication fees" regarding the submission "DYNAMIC MODELING OF A SINGLE-LINK FLEXIBLE MANIPULATOR ROBOT WITH TRANSLATIONAL AND ROTATIONAL MOTIONS".

Link: <https://journals.iium.edu.my/ejournal/index.php/iiumej/authorDashboard/submission/1254>

Prof. Dr. AHM Zahirul Alam

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IIUM Engineering Journal



Dermawan Pnup <dermawan@poliupg.ac.id>

---

## [IIUMEJ] New notification from IIUM Engineering Journal

---

**Prof. Dr AHM Zahirul Alam** <iiumej@iium.edu.my>

10 Desember 2019 08.55

Balas Ke: "Prof. Dr. AHM Zahirul Alam" <zahirulalam@iium.edu.my>

Kepada: Dermawan Dermawan <dermawan@poliupg.ac.id>

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Prof. Dr. AHM Zahirul Alam

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IIUM Engineering Journal



Dermawan Pnup <dermawan@poliupg.ac.id>

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## [IIUMEJ] New notification from IIUM Engineering Journal

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**Prof. Dr AHM Zahirul Alam** <iiumej@iium.edu.my>

10 Desember 2019 08.55

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Kepada: Dermawan Dermawan <dermawan@poliupg.ac.id>

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Prof. Dr. AHM Zahirul Alam

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IIUM Engineering Journal



Dermawan Pnup <dermawan@poliupg.ac.id>

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## [IIUMEJ] New notification from IIUM Engineering Journal

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**Prof. Dr AHM Zahirul Alam** <iiumej@iium.edu.my>

27 November 2019 06.41

Balas Ke: "Prof. Dr. AHM Zahirul Alam" <zahirulalam@iium.edu.my>

Kepada: Dermawan Dermawan <dermawan@poliupg.ac.id>

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