#### **BUKTI KORESPONDENSI**

Judul Artikel	Computer Simulations and Experiments on Vibration Control of a Flexible Link Manipulator Using a Piezoelectric Actuator
Penulis Utama dan	Abdul Kadir Muhammad
Korespondensi	Abdul Radii Wullallillad
Jenis Artikel	Konferensi Internasional
Nama Konferensi	International Multi Conference of Engineers and Computer Scientist
Nama Komerensi	(IMECS 2014)
Waktu Pelaksanaan	12 - 14 Maret 2014
Tempat Pelaksanaan	Hong Kong, China

# Acknowledgment of receiving your submission for IMECS 2014

Yahoo/Email Masuk

### IAENG Conferences - IMECS 2014 <imecs@iaeng.org>

# Kepada:y861008b@mails.cc.ehime-u.ac.jp

Rab, 8 Jan 2014 jam 17.04

Dear Dr. Abdul Kadir Muhammad,

Thanks for your submission to the International MultiConference of Engineers and Computer Scientists 2014 (IMECS 2014).

Your paper number in IMECS 2014 is ICCA\_32 (the track: The 2014 IAENG International Conference on Control and Automation)

with the paper title, Computer Simulations and Experiments on Vibration Control of a Flexible Link Manipulator Using a Piezoelectric Actuator.

It is expected that our reviewing procedure for this manuscript  $\ensuremath{\mathsf{will}}$ 

be fast. It is our target that the result notification can be completed

within one month and by the registration due. For the accepted and registered papers, they will be included in the conference proceeding published by IAENG (ISBN: 978-988-19252-5-1) in hardcopy. The length of

each camera-ready paper will be limited to 6 (IEEE style, double-column)

pages. Each conference participant will be entitled to one proceeding at

the conference. The accepted papers will also be considered for further

publication, e.g. in the special issues of the IAENG journals and in edited  $\,$ 

book. The proceeding will be indexed in major database indexes so that  $% \left( 1\right) =\left( 1\right) +\left( 1\right) +\left($ 

it can be assessed easily.

The International MultiConference of Engineers and Computer Scientists 2014 will take place in Hong Kong, 12-14 March, 2014. http://www.iaeng.org/IMECS2014/

The publication ethics and publication malpractice statement is available at

http://www.iaeng.org/IMECS2014/doc/publication\_ethics.html

Our IMECS committees have been formed with over three hundred committees  $\ensuremath{\mathsf{N}}$ 

members who are mainly research center heads, faculty deans, department

heads, professors, and research scientists from over 30 countries.

We will notify you once we have the review result. We are looking forward

to your participation in IMECS 2014 and would like to express our warmest  $\,$ 

welcome to you in advance.

Best regards,

Anna Lee
Assistant Secretary
IMECS 2014 Organizing Committee
IAENG Publication Committee
http://www.iaeng.org/IMECS2014
http://www.iaeng.org/publications.html

# Review result for the manuscript submissions in IMECS 2014

Yahoo/Email Masuk

# **IAENG Conference - IMECS 2014** <imecs@iaeng.org>

Kepada:y861008b@mails.cc.ehime-u.ac.jp

Min, 19 Jan 2014 jam 16.59

Dear Dr. Abdul Kadir Muhammad,

[Review result for the manuscript submissions in IMECS 2014]

Thanks for your submission to the International MultiConference of

Engineers and Computer Scientists 2014 (IMECS 2014). It is our pleasure to tell you that your manuscript

- paper number: ICCA 32
- title: Computer Simulations and Experiments on Vibration Control of a Flexible Link Manipulator Using a Piezoelectric Actuator

has been accepted for the IMECS 2014. Please read the attached review report.

There is an appeal system that we will arrange two other reviewers for your submitted paper if you do not agree with the grading or comment(s) in this review.

For the accepted and registered papers, they will be included in the conference proceeding published by IAENG (ISBN: 978-988-19252-5-1) in hardcopy. The length of each camera-ready paper will be limited to 6 (IEEE style, double-column) pages. Each conference participant will be entitled to one proceeding at the conference. The accepted papers will also be considered for further publication, e.g. in the IAENG journals and in edited book. The proceeding will be indexed in major database indexes so that it can be assessed easily.

## **Important Dates:**

Camera-Ready Papers Due & Registration Deadline (extended): 30 January, 2014

IMECS 2014: 12-14 March, 2014

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The details about the registration are available at: http://www.iaeng.org/IMECS2014/registration.html

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The details about the camera-ready paper format and templates are available at:

http://www.iaeng.org/IMECS2014/publication.html

To ensure the correctness of the format, you are required to check your revised paper against the checklist available for download at http://www.iaeng.org/publication/download/Checklist\_camera-ready\_general.pdf

You are advised to send it immediately once it is ready instead of waiting till the deadline. Usually, authors need to submit the revised versions more than once before the papers getting accepted.

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Only accepted and registered papers in camera-ready will be included in the proceedings book

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The details about the accommodation are available at: http://www.iaeng.org/IMECS2014/travel.html

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More details about the IMECS Best Paper Awards are available at: http://www.iaeng.org/IMECS2014/program.html

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We are looking forward to your presentation of this paper and would like to express our warm welcome to you in advance.

If you have any question, you are also welcome to tell us.

Best regards,

Anna Lee Assistant Secretary IMECS 2014 Organizing Committee http://www.iaeng.org/IMECS2014/

Engineering Letters http://www.engineeringletters.com/

IAENG International Journal of Computer Science http://www.iaeng.org/IJCS/

IAENG International Journal of Applied Mathematics http://www.iaeng.org/IJAM/

IAENG Secretariat Unit 1, 1/F, 37-39 Hung To Road, Hong Kong

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The International MultiConference of Engineers and Computer Scientists 2014 (IMECS2014)

Paper No.: ICCA\_32 (The 2014 IAENG International Conference on Control and Automation)

Paper Title: Computer Simulations and Experiments on Vibration Control of a Flexible Link Manipulator Using a Piezoelectric Actuator

Recommendation (tick one)
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Accept : [ yes ]

Accept with minor revision : [ ]

Accept with major revision : [ ]

Reject : [ ]

Recommendation for Best Paper Awards competition : [ yes ]

Recommendation for the IAENG Journal : [ yes ]

Recommendation for the edited book : [ yes ]

Brief summary and further comments for the author(s) if any for improvement of the paper:

In the paper, the authors derived the equation of motion for the flexible link manipulator using the finite-element method. The experimental results are satisfactory.