

BUKTI KORESPONDENSI

Judul Artikel	Comparisons of Proportional and Active-force Controls on Vibration of Flexible Link Manipulator Using a Piezoelectric Actuator through Calculations and Experiments
Penulis Utama dan Korespondensi	Abdul Kadir Muhammad
Jenis Artikel	Jurnal Internasional
Nama Jurnal	Engineering Letters
Tanggal Terbit	September 2014
Penerbit	International Association of Engineers
Negara	Hong Kong, China

Invitation for submitting paper for the publication in IAEng Journal  
(Engineering Letters)

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**Kepada:** y861008b@mails.cc.ehime-u.ac.jp

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Jum, 11 Apr 2014 jam 09.28

Dear Mr. Abdul Kadir Muhammad,

We would like to invite you to submit your research work for the publication in the IAENG Journals. For your reference, the details of the journals are available at:  
<http://www.iaeng.org/publications.html>

Should you have any enquiry, please feel free to contact us.

Best regards,  
Joan Mok  
Assistant Secretary  
International Association of Engineers (IAENG)  
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Submit paper the IAEng Journal (Engineering Letters), Received June 26<sup>3</sup>

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Jum, 27 Jun 2014 jam 13.51

Dear Ms Joan Moak

at IAEng Secretariat

Herewith I send my paper for Engineering Letters.

The title of the paper is

"Comparisons of Proportional and Active-force Controls on Vibration of a Flexible Link Manipulator Using a Piezoelectric Actuator through Calculations and Experiments"

Please let me know after you get my paper.

Thank you very much.

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Abdul Kadir Muhammad

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Rab, 2 Jul 2014 jam 12.27

Dear Sir/Madam,

Thanks for your file(s). Tentatively, the paper will be published in the next issue if there is no problem. If there is any problem, we will inform you. After its publication, we will send publication information by email. Please find the review result.

Should you have any enquiry, please feel free to contact us.

Best regards,

Joan Mok

Assistant Secretary

International Association of Engineers (IAENG)

<http://www.iaeng.org>

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Engineering Letters

Paper Title: Comparisons of Proportional and Active-force Controls on Vibration of a Flexible Link Manipulator Using a Piezoelectric Actuator through Calculations and Experiments

Ratings: 5=excellent, 4=good, 3=average, 2=poor, 1= unacceptable

1. Content

Technical quality (1-5) : [ 5 ]

Technical originality (1-5) : [ 5 ]

2. Presentation

Overall format (1-5) : [ 4 ]

Abstract (1-5) : [ 5 ]

English (1-5) : [ 4 ]

3. Recommendation (tick one)

Accept : [ yes ]

Accept with minor revision : [ ]

Accept with major revision : [ ]

Reject : [ ]

4. Brief summary and further comments for the author(s) if any for improvement of the paper.

(Use a separate sheet if necessary)

In the paper, the authors derived the equation of motion for the flexible link manipulator using the finite-element method, controlled by proportional and active force control. The experimental results are satisfactory.